

| | Secondary Air Injection System Monitoring Operation | | | | | | | | | | | |
|----------------------|---|---|-------------------------|-------------------------------------|------------------------|----------------------|------------------|---------------------|--|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | | |
| Secondary | P0418 | circuit continuity | voltage - drive on | voltage > 1/2 * Battery positive | engine speed | > 80 rpm | immediately/ | two driving | | | | |
| Air Injection | | short to battery positive | | | battery voltage | 7.5V < B+ < 17V | continuous | cycles | | | | |
| Pump Relay | | circuit continuity | voltage - drive off | voltage < 1/3 * Battery positive | | | | | | | | |
| | | - short to ground | | | | | | | | | | |
| | | circuit continuity | voltage - drive off | 1/3 * Battery positive< | | | | | | | | |
| | | - open circuit | | < 2/3 * Battery positive | | | | | | | | |
| Secondary | P0412 | circuit continuity | voltage - drive on | voltage > 1/2 * Battery positive | engine speed | > 80 rpm | immediately/ | two driving | | | | |
| Air Injection | | short to battery positive | | | battery voltage | 7.5V < B+ < 17V | continuous | cycles | | | | |
| Valve | P0414 | circuit continuity | voltage - drive off | voltage < 1/3 * Battery positive | | | | | | | | |
| Vacuum | | - short to ground | | | | | | | | | | |
| Solenoid | P0413 | circuit continuity | voltage - drive off | 1/3 * B+ < voltage | | | | | | | | |
| Drive | | - open circuit | avatam is OK if | < 2/3 * Battery positive | | E20 < man < 2E20 | 11 | turo drivino a | | | | |
| Air Injection | | voltage | bank 1 O2S Value | < 0.501 V (for > 55 times | engine speed | 520 < 1011 < 2520 | 14 Sec/ Once | cvcles | | | | |
| System | | Minimum | | in 80 Samples) | engine airflow | < 55.56 g/sec | cvcle | Cycles | | | | |
| (Passive | | value is sampled | | | ECT | > 8 °C | | | | | | |
| Test) | | over a time | and | | front O2S | ready for operation | | | | | | |
| Bank 1 | P1412 | of 0.100 sec .lf | bank 2 O2S Value | < 0.399 V (for > 55 times | | for > 10.0 sec | | | | | | |
| Bank 2 | P1415 | this value is | | in 80 samples) | secondary air | operating | | | | | | |
| | | greater than | | | time after engine | < 655 sec | | | | | | |
| | | a threshold, then | | | start | > 0 711 | | | | | | |
| Cocondorra | | the system is ok | | | altitude factor | > 0./11 | 10 5 225/ | tu o drivir a | | | | |
| Secondary | | valve cneck:- | change in fuelling | - 0.05 | venicie speed | = u mpn | 10.5 Sec/ | iwo ariving | | | | |
| System | | secondary air | | 0.05 | secondary air | not operating but | driving cycle | cycles | | | | |
| System | | secondary all | CONECTION | | secondary all | not operating, but | | | | | | |



| | Secondary Air Injection System Monitoring Operation | | | | | | | | | | |
|-----------------------------------|---|---|-------------------------|-----------------|--|--|------------------|---------------------|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | |
| (Active Test) Bank 1 Bank 2 | P1413 P1416 | injection pump with the control valves shut and monitor the Fuelling | | | injection fuel system status passive | has operated this drive cycle Closed loop not completed | | | | | |
| Donk 1 | D1414 | Correction | abanaa in fuolling | < 0.00 | secondary air diagnostic altitude factor | > 0.711 | | | | | |
| Bank 1 Bank 2 | P1414 P1417 | check is successful, continue running the pump, but with the valves open and monitor the Fuelling correction. | correction | < 0.08 | active test counter | > 580 sec ramped to zero & wait 3.0 sec > 0 | | | | | |



4.4 Evaporative Emission System Monitoring – 0.040" (1.0mm) Diameter

4.4.1 Description

The evaporative emission system monitoring permits the detection of leaks in the fuel evaporative emission control system with a diameter of 0.040" or larger.

For this purpose, a system pressure check is performed at idle with the vehicle stationary. Since vapour generation in the fuel tank could cause the false detection of a system leak, the first step is to close the EVAP canister purge valve and EVAP canister vent solenoid valve. Any pressure build-up is then measured, so that later results can be compensated for this fuel evaporation effect.

The EVAP canister purge value is opened and the EVAP canister vent solenoid value is closed. With this procedure a vacuum in the tank is created, which is measured by the fuel tank pressure sensor.

If no vacuum is detected, a large leak is assumed and the diagnosis is halted. If a large lean correction of the oxygen sensor controller is detected during the vacuum build-up, then the check is also halted, since fuel vapour is present in the system due to a high EVAP canister loading and idle instability will occur if the test is continued.

At a pre-determined vacuum the EVAP canister purge valve is closed, and the system is now considered "closed". From the gradient of the vacuum decay and the previously measured fuel vapour generation pressure rise, the presence of a leak can be inferred. The decay of the vacuum gradient also depends on the fuel level in the tank. The fuel level is roughly derived from the gradients of the vacuum build-up and vacuum decay and this information is also used when determining if a leak is present.



4.4.2 Monitoring Structure

Typical fuel tank pressure characteristic during the diagnostic test









| | Evaporative Emission System Monitoring – 0.040" (1.0mm) Diameter | | | | | | | | | | | |
|--|--|--|--|---|---|--|--|-----------------------|--|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | | |
| Evaporative | P0443 | Circuit continuity | voltage - drive on | voltage > 1/ 2 * Battery positive | engine speed | > 80 rpm | immediately/ | two driving | | | | |
| Emission | | - short to battery positive | | | battery voltage | 7.5V < Battery positive < 17V | continuous | cycles | | | | |
| Canister | P0445 | Circuit continuity | voltage - drive off | voltage < 1/3 * Battery positive | | | | | | | | |
| Purge Valve | P0444 | short to ground circuit continuity open circuit | voltage - drive off | 1/3 * B+ < voltage < 2/3 * Battery positive | | | | | | | | |
| | P0440 | Functional check – valve open or Leaking | fuel tank pressure during pressure compensation measurement for the EVAP Purge system check fuel tank pressure | < - 1.464 hPa < - 15.62 hPa | see evaporative emission system purge check | | up to 24.5 sec/once per driving cycle up to 36.5 | two driving cycles | | | | |
| | | | at the end of the large system leak test | | | | sec/once per driving cycle | | | | | |
| Evaporative Emission Purge System | P0455 P0442 | vacuum check uses the EVAP canister vent solenoid valve & the fuel tank pressure sensor | large system leak (e.g. missing filler cap) small system leak (⁻ 1mm) | vacuum build up gradient < 0.305 hPa/sec vacuum decay grad (pressure comp. grad. * comp. factor) > Threshold | EVAP canister purge vapour factor fuel tank pressure lambda control engine state battery voltage vehicle speed altitude factor intake air | < 5.0 m 15.13 hPa active idle ⁻ 11.0V Zero ⁻ 0.73 ⁻ -12.0 °C | up to 36.5 sec/once per driving cycle up to 41.5 sec/once per driving cycle | two driving cycles | | | | |
| | | | | | temperature engine load fuel tank level | m2.80 msec not empty | | | | | | |



| | Evaporative Emission System Monitoring – 0.040" (1.0mm) Diameter | | | | | | | | | | | |
|----------------------|--|---|------------------------------|-------------------------------------|--|---|------------------|---------------------|--|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | | |
| | | | | | engine air flow rate ECT at engine start | m40.0 kg/hr -12.0 °C < start temp. < 65.25 °C | | | | | | |
| | | | | | time after engine start transfer gears | > 960 sec | | | | | | |
| Evaporative | P0449 | circuit continuity | voltage - drive on | voltage > 1/2 * Battery positive | engine speed | > 80 rpm | immediately/ | two driving | | | | |
| Emission | | short to battery positive | | voltogo < 1/2 * Pottony | battery voltage | 7.5V < Battery positive < 17V | continuous | cycles | | | | |
| Canister | P0448 | circuit continuity | voltage - drive off | positive | | | | | | | | |
| Vent | | - short to ground | | 1/3* Battery positive < | | | | | | | | |
| Solenoid | P0447 | circuit continuity | voltage - drive off | voltage < 2/3* | | | | | | | | |
| Valve | | - open circuit | | Battery positive | | | | | | | | |
| | P0446 | functional | fuel tank pressure | tank pressure | see evaporative | | up to 36.5 | | | | | |
| | | for a blocked | large system | < - 1.404 IIPa | system check | | driving cycle | | | | | |
| | | EVAP canister | leak test | | eyetem eneek | | | | | | | |
| | | vent solenoid | fuel tank pressure | tank pressure | | | 20 sec/ | | | | | |
| | | valve | too low during | < - 14.64 hPa | | | once per | | | | | |
| | | | stabilisation | | | | driving cycle | | | | | |
| | | | svstem check | | | | | | | | | |
| Fuel Tank | P0452 | fuel tank | fuel tank pressure | < -28.30 hPa | transfer gears | high range | 5.0 sec/ | two driving | | | | |
| Pressure | | pressure signal | (min) | | | | continuous | cycles | | | | |
| Sensor | P0453 | high/low | fuel tank pressure | > 29.52 hPa | | | | | | | | |
| | P0451 | sensor | (IIIdX) filtered pressure | ⁻ 15 13 hPa | transfer dears | high range | 5.0 sec/ | two driving | | | | |
| | 10401 | functional check | reading | 15.15 HF a | engine state | idle | once per | cycles | | | | |
| | | | | | ECT at engine start | m 35.25 °C | driving cycle | , | | | | |



| | Evaporative Emission System Monitoring – 0.040'' (1.0mm) Diameter | | | | | | | | | | |
|----------------------|---|---------------------------------------|-------------------------|-----------------|---|-------------------------------------|------------------|---------------------|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | |
| | | | | | time after start time for stabilisation | m 20.0 sec ⁻ 10.0 sec | | | | | |



4.5 Evaporative Emission System Monitoring - 0.020" (0.5mm) Diameter

4.5.1 Description

The evaporative emission monitoring system used for the Discovery 2001MY onwards permits the detection of leaks with a diameter of 0.020" or greater. This is achieved by means of a pressure test of the system. This is performed by the DMTL, which is an electrically operated pump fitted to the atmospheric air intake of the EVAP Canister. From the 2002MY this unit contains an electric heater to prevent condensate formation.

The test proceeds in 2 stages:-

- *∉*[#] Reference Leak Measurement The pump operates against the reference restriction within the DMTL. The ECM measures the current consumption of the pump motor during this phase.
- ∉ Leak Measurement (see diagram below) The solenoid in the DMTL is operated in order to shut off normal purge airflow into the EVAP Canister. The pump can now pressurise the fuel tank and vapour handling system. The ECM again measures the current consumed by the pump motor and by comparing this with the reference current, determines if a leak is present or not. A high current indicates tight system and a low current indicates a leaking system.





Typical Pump Current

















| | Evaporative Emission System Monitoring – 0.020" (0.5mm) Diameter | | | | | | | | | | | |
|----------------------|--|---|-------------------------|--------------------------------------|------------------------|----------------------------------|------------------|---------------------|--|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | | |
| Evaporative | P0443 | circuit continuity | voltage - drive on | voltage > 1/ 2 * Battery positive | engine speed | > 80 rpm | immediately/ | two driving | | | | |
| Emission | | short to battery positive | | | battery voltage | 7.5V < Battery positive < 17V | continuous | cycles | | | | |
| Canister | P0445 | circuit continuity | voltage - drive off | voltage < 1/3 * Battery | | | | | | | | |
| Purge Valve | | - short to ground | | poorato | | | | | | | | |
| | P0444 | circuit continuity | voltage - drive off | 1/3 * Battery positive < voltage < | | | | | | | | |
| | | - open circuit | | 2/3 * Battery positive | | | | | | | | |
| Evaporative | P0441 | functional check | feedback correction | | engine state | ldle | 15 sec/ | two driving | | | | |
| Emission | | - no purge flow | factor | m 1.125 | ECT at start | ⁻ -12.0 °C | once per | cycles | | | | |
| Canister | | detected. Open | <u>OR</u> | > 0.875 | altitude factor | -0.7266 | driving cycle | | | | | |
| Purge Valve | | EVAP canister | <u>AND</u> | | engine load | m2.80 msec | | | | | | |
| | | purge valve and | Idle air flow change | m0.17 g/sec | engine air flow | m12.5 g/sec | | | | | | |
| | | check for feed- | | | venicle speed | 0 mpn | | | | | | |
| | | DACK SNITT, IT | | | speed fluctuation | m80 rpm | | | | | | |
| | | shint is within a | | | | > 1000 sec | | | | | | |
| | | for | | | /time after start | > 500 sec | | | | | | |
| | | stoichiometric | | | & mixture adant | complete | | | | | | |
| | | nurge by | | | & nurge factor | m3.0 | | | | | | |
| | | monitoring idle | | | & ISC diagnostic) | complete | | | | | | |
| | | speed control. | | | | | | | | | | |
| | | If air flow has | | | | | | | | | | |
| | | not changed due | | | | | | | | | | |
| | | to the purge flow | | | | | | | | | | |
| | | then a fault exists | | | | | | | | | | |
| Leak | P1451 | circuit continuity | voltage - drive off | 1/3 * Battery positive < voltage | engine speed | > 80 rpm | 0.5 sec/ | two driving | | | | |
| Detection | | - open circuit | | < 2/3 * Battery positive | battery voltage | 7.5V < Battery | continuous | cycles | | | | |



| | Evaporative Emission System Monitoring – 0.020'' (0.5mm) Diameter | | | | | | | | | | | |
|---|---|---|--|--|--|---|----------------------------|-----------------------------------|--|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | | |
| Pump Power Stage | | circuit continuity - short to ground circuit continuity - short to battery positive | voltage - drive off voltage - drive on | voltage < 1/3 * Battery positive > 3.998V | battery voltage | positive <17V m15.47V (max for pump control) | 0.07 sec/ continuous | | | | | |
| Leak Detection | P1483 | circuit continuity - short to battery | voltage - drive on | voltage > 1/2 * Battery positive | engine speed battery voltage | > 80 rpm 7.5V < Battery positive< 17V | immediately/ continuous | No MIL illumination | | | | |
| Pump Heater Circuit | P1482 P1481 | circuit continuity - short to ground circuit continuity | voltage - drive off voltage - drive off | voltage < 1/3 * Battery positive 1/3 * Battery positive < voltage | | | | (leak detection defaults to | | | | |
| EVAP Canister Purge System (Discovery | P1452 | over-pressure system using an ECM driven Pump Pump hardware | pump ref. current | < 15.002 mA | ECM state engine state altitude factor ECT at engine start | In After Run for > 3.0 sec At Rest [−] 0.7266 [−] 2.25 °C | | four driving cycles | | | | |
| only) | P1453 P1450 | Fault Pump hardware Fault Pump hardware Fault | pump ref. current pump current (during rough leak) | > 40.002 mA ⁻ ref current - 2.002 mA | ambient temp. (calculated) EVAP canister purge vapour factor time after start vehicle speed | 0.0 °C < Amb Temp < 40.0 °C < 3.0 ⁻ 1200 sec 0 mph | | | | | | |
| | | | | | battery voltage | 10.94V < Battery positive <14.52V (for 3.0 sec) | | | | | | |



| | Evaporative Emission System Monitoring – 0.020" (0.5mm) Diameter | | | | | | | | | | | |
|----------------------|--|---------------------------------------|--|---|---|---|---|---------------------|--|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | | |
| | | | | | fuel level in window transfer gears | 15 % < fuel level < 85 % high range | | | | | | |
| | P0455 | rough leak Measurement | pump current at end of test stage 1 stage 2 | < idle current + K1(ref. current - idle current) < ref. current + K2(ref current - idle current) K1 = 0.26 +/- 0.09 | soak time no gas cap removal (during test) no re-fuelling (during test) | [−] 9000 sec change of pump current< -0.598 mA change of pump current > 0.598 mA | 160 sec/ once per driving cycle | | | | | |
| | P0442 | small leak Measurement | pump current | K1 = 0.20 // 0.00 $K2 = 0.52 +/- 0.13$ mreference Current OR | re-fuelling (prior to test) rough leak counter | detected | rough leak + 375 sec/ once per driving cycle | | | | | |
| | | | | | no gas cap removal (during test) no re-fuelling (during test) | change of pump current < -0.598 mA change of pump current > 0.598 mA | | | | | | |



4.6 Fuel System Monitoring

4.6.1 Description

Primary Mixture Control

The air mass taken in by the engine and the engine speed are measured. These signals are used to calculate an injection signal. This primary mixture control follows fast load and speed changes.

Lambda-control

The ECM compares the oxygen sensor signal upstream of the catalyst with a reference value and calculates a correction factor for the primary control.



Adaptive Control

Drifts and faults in the sensors and actuators of the fuel delivery system, as well as un-metered air leakage into the intake system influence the primary control. This causes deviations in the air to fuel ratio. The adaptive control determines the controller correction in two different ranges.



Range 1 - Additive Correction per time unit Range 2 - Multiplicative Correction

Lambda deviations in range 1 are compensated by an additive correction value multiplied by an engine speed term. By this means an additive correction per time unit is derived.

Lambda deviations in range 2 are compensated by a multiplicative factor.

Each value is determined only within its corresponding range. But each adaptive value corrects the primary control within the whole load and speed range of the engine. After the next start, the stored adaptive values are included in the calculation of the primary fuel control; just before closed-loop fuelling control is activated.

Abbreviations for the Fuel Delivery System:

- QU1 upper airflow threshold range 1
- NU1 upper engine speed threshold range 1



tra additive learning correction coefficient per time unit (range 1) TRADN lower diagnosis threshold of tra TRADX upper diagnosis threshold of tra TLARN upper engine load threshold f(n), range 2 QL2 lower airflow threshold range 2 TLL2 lower engine load threshold range 2 fra multiplicative learning correction coefficient (range 2) FRADN lower diagnosis threshold of fra FRADX upper diagnosis threshold of fra

Diagnosis of Fuel Delivery System

Faults in the fuel delivery system can occur which cannot be compensated for by the adaptive control. In this case the adaptive values leave a predetermined range. If the adaptive value is outside this predetermined range, and then if the condition is again present on a subsequent drive cycle, the MIL is illuminated and the appropriate diagnostic trouble codes are stored.



4.6.2 Monitoring Structure





| | Fuel System Monitoring | | | | | | | | | | |
|----------------------|------------------------|--|---|-----------------------------|---|---|------------------|-----------------------|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | |
| Fuel System | | fuel trim limits exceeded | | | fuel system status ECT IAT transfer gears purge diagnosis | closed loop+part load > 80.25 °C m 69.75 °C high range not active | | two driving cycles | | | |
| | P0171/2 P0174/5 | bank 1 lean/rich bank 2 lean/rich | fra value (multiplicative correction) outside limit | > ± 22.7 % | engine speed engine load engine airflow rate | < 3800 rpm 2.0 < TL ms < 10.0 > 16.67 g/sec | 10.0 sec | | | | |
| | P1171/2 P1174/5 | bank 1 lean/rich bank 2 lean/rich | tra value (additive correction) outside limit | > ± 0.452 ms /engine rev | engine speed engine airflow rate | < 960 rpm < 8.33 g/sec | 8.0 sec | | | | |



4.7 Oxygen Sensor Monitoring

4.7.1 Description

The response rates of the upstream O2 sensors are monitored by measuring the period of the Lambda control oscillations. This period monitoring allows the detection of a slow O2 sensor.





4.7.2 Monitoring Structure





4.7.3 Oxygen Sensor Heater Monitoring Description

For proper functioning of an oxygen sensor, its element must be heated. A non-functioning heater delays the oxygen sensor's readiness for closed loop control and influences emissions.

The monitoring function measures both oxygen sensor heater current (voltage drop over a shunt) and the heater voltage (heater supply voltage), so that the oxygen sensor heater resistance can be calculated. If the oxygen sensor heater resistance is exceeds a minimum or maximum threshold an oxygen sensor heater fault is detected.

The monitoring function is activated once per drive cycle, as long as the heater has been switched on for a certain time period and the current has stabilized.

Characteristics:-

- *e* ECM controlled switching of the oxygen sensor heater.
- *e*# One shunt for each pair of oxygen sensors upstream and downstream of the catalysts for current measurement.



4.7.4 Oxygen Sensor Heater Monitoring Structure





The oxygen sensor heater resistance is calculated from the following equation:-

Resistance_{sensor heater} = $\frac{\text{Voltage}_{\text{battery}}}{\text{Voltage}_{\text{shunt}}} \Delta \text{Resistance}_{\text{shunt}}$

Oxygen Sensor Circuit Monitoring

Monitoring for electrical faults in the oxygen sensors both upstream and downstream of the catalyst.

Implausible voltages:

- Analogue to Digital Converter (ADC) voltages exceeding the maximum threshold VMAX are caused by a short circuit to battery positive.
- ADC voltages falling below the minimum threshold VMIN are caused by a short circuit of the oxygen sensor signal or oxygen sensor ground to the ECM ground.
- An open circuit of the oxygen sensor can be detected if the ADC voltage remains within a specified range after the oxygen sensor has been heated for a certain time.



| | | | Оху | gen Sensor Monitoring | g – Discovery Serie | es II | | |
|-----------------------------|----------------|---|--|--|--|---|---|-----------------------|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold Value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination |
| Oxygen Sensor (front) | P0133/53 | response rate | oxygen sensor signal period (over 50 periods) | > 2.2 sec | engine speed engine load catalyst temperature (model) IAT EVAP canister purge status transfer gears | 1400< rpm <2600 2.0< TL msec <5.0 > 340 °C m 65.25 °C Off <u>or</u> on > 20 sec high range | immediately/ once per driving cycle | two driving cycles |
| - - | P1170/73 | sensor ageing | rich shift delay Time | < -1.0 or > 1.0 sec | O2S post catalyst control transfer gears | active high range | 30 sec | |
| | P1129 | exchanged oxygen sensors connector | fuel control factor <u>or</u> | bank 1 > 1.22 and bank 2 < 0.77 bank 1 < 0.77 and bank 2 > 1.22 | | | 8.0 sec | |
| | | | | | heater on transfer gears | > 90 sec high range | | |
| | P0134/54 | O2S circuit continuity | voltage <u>or</u> voltage (front & rear) | 0.399V < voltage <0.598V voltage > 0.199V | over run fuel cut off | > 3.0 sec | 15 sec/continuous 0.1 sec/continuous | |
| | P0132/52 | range check (high) | voltage | voltage > 1.081V | | | 5.1 sec/continuous | |
| | P0130/50 | O2S short circuit | voltage | voltage < 0.0399V | O2S post catalyst voltage | ⁻ 0.501V | 20 sec/continuous | |
| | | | | <u>Or</u> | ECT battery voltage time after start ECT at power down | < 39.75 °C > 8.016V > 1.0 sec > 60 °C | 0.1 sec/continuous | |
| | | | | 0.062V m voltage < 0.399V | O2S post catalyst voltage | ⁻ 0.501V | 20 sec/continuous | |



| | | | Oxy | gen Sensor Monitoring | g – Discovery Serie | es II | | |
|----------------------|----------------|--|---|--|---|--|------------------------|---------------------|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold Value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination |
| | | • | | 0.598V m voltage m 1.081V | O2S post catalyst voltage | < 0.102V | 10 sec/continuous | |
| Heater | P0135/55 | O2S heater current circuit continuity | calculated resistance voltage | resistance < 2.453 ô <u>or</u> resistance > 10.06 ô | after engine start up transfer gears | > 180 sec high range | 10 sec/continuous | |
| Oxygen | | | | | O2S heater on | > 90 sec | | two driving |
| (rear) | P0140/60 | O2S circuit continuity | voltage | 0.399V < voltage < 0.501V | transier gears | nigh range | 500 sec/ continuous | cycles |
| | P0138/58 | range check (high) | voltage | voltage > 1.081V | | | 5.1 sec/continuous | |
| | P0137/57 | range check (low) | voltage | voltage < 0.501V | engine air flow O2S post catalyst control | > 16.67 g/sec Active | 210 sec/ continuous | |
| | P0136/56 | O2S short circuit | voltage | voltage < 0.0399 | O2S post catalyst control | Active | 200 sec/ continuous | |
| | P0139/59 | oscillation capability check | | | O2S post catalyst control catalyst temperature (model) | Active > 300 °C | | |
| | | | | | engine air flow rear O2S ready for at least | > 13.89 g/sec 30.0 sec | | |
| | | | | | rear O2S heater test rear O2S rich & lean flags not set | completed successfully > 120 sec | | |
| | | | if rear O2S voltage not [−] 0.625V for | enrichment request still present after 25 sec | catalyst temperature (model) | > 300 °C | 2.0 sec/continuous | |



| | Oxygen Sensor Monitoring – Discovery Series II | | | | | | | | | | |
|----------------------|--|---------------------------------------|------------------------------------|--------------------------------|------------------------|---|-------------------|---------------------|--|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold Value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | | |
| | | | 0.52 se c request enrichment | | | | | | | | |
| | | | if rear O2S | rear O2S voltage | fuel system status | in over run fuel cut off (ORFCO) for | 0.20 sec/ | | | | |
| | | | voltage not | > 0.200V | | > 4.0 sec | continuous | | | | |
| | | | m 0.625 V for | | integrated engine air | > 35.0 g | | | | | |
| | | | 0.52 sec | | flow whilst in | | | | | | |
| | | | wait for over | | ORFCO | | | | | | |
| | | | run fuel cut off | | front O2S check | completed | | | | | |
| | | | (ORFCO) | | | successfully | | | | | |
| Heater | P0141/61 | O2S heater | calculated | resistance < 2.453 ô | after engine start up | > 180 sec | 10 sec/continuous | | | | |
| | | current | resistance | <u>or</u> resistance > 10.06 ô | transfer gears | high range | | | | | |
| | | circuit | voltage | | | | | | | | |
| | | continuity | | | | | | | | | |

| Oxygen Sensor Monitoring – Range Rover | | | | | | | | | |
|--|----------------|---------------------------------------|---|--------------------|--|---|---|-----------------------|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold Value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | |
| Oxygen Sensor (front) | P0133/53 | response rate | O2S signal period (over 30 periods) | > 2.2 sec | engine speed engine load catalyst temperature (model) intake air temperature EVAP canister purge status | 1400 < rpm < 2600 2.0 < TL msec < 5.0 > 340 °C m 69.75 °C off <u>or</u> on > 20 sec | Immediately/ once per driving cycle | two driving cycles | |



| Oxygen Sensor Monitoring – Range Rover | | | | | | | | | |
|--|----------------|--|--|--|---|---|---|---------------------|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold Value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | |
| | | | | | transfer gears | high range | | | |
| | P1170/73 | O2S ageing | rich shift delay time | < -1.0 or > 1.0 sec | O2S post catalyst control transfer gears | active | 30 sec | | |
| | P1129 | exchanged O2S connectors | fuel control factor <u>or</u> | bank 1 > 1.22 and bank 2 < 0.77 bank 1 < 0.77 and bank 2 > 1.22 | O2S heater on transfer gears | > 120 sec high range | 8.0 sec | | |
| | P0134/54 | O2S circuit continuity | voltage <u>or</u> voltage (front & rear) | 0.399V< voltage < 0.598V voltage > 0.199V | over run fuel cut off | > 3.0 sec | 15 sec/continuous 0.1 sec/continuous | | |
| | P0132/52 | range check (high) | voltage | voltage > 1.081V | | | 5.1 sec/continuous | | |
| | P0130/50 | O2S short circuit | voltage | voltage < 0.0399 | O2S post catalyst voltage | >= 0.501V | 20 sec/continuous | | |
| | | | | <u>Or</u> | ECT battery voltage time after start ECT at power down | < 39.75 °C > 8.016V > 1.0 sec > 80.25 °C | 0.1 sec/continuous | | |
| | | | | 0.062V m voltage< 0.399V | O2S post catalyst voltage | ⁻ 0.501V | 20 sec/continuous | | |
| | | | | 0.598Vm voltage m 1.081V | O2S post catalyst voltage | < 0.102V | 10 sec/continuous | | |
| Oxygen Sensor (front) Heater | P0135/55 | O2S heater current circuit continuity | calculated resistance voltage | resistance < 2.453 ô <u>or</u> resistance > 10.06 ô | after engine start up transfer gears | > 185 sec high range | 10 sec/continuous | two driving cycles | |
| Oxygen Sensor | P0140/60 | O2S circuit continuity | voltage | 0.399V < voltage< 0.501V | | | 500 sec/ continuous | two driving cycles | |
| (rear) | P0138/58 | range check (high) | voltage | voltage > 1.081V | | | 5.1 sec/continuous | | |
| | P0137/57 | range check (low) | voltage | voltage < 0.501V | engine air flow post-cat control | > 60 kg/hr Active | 210 sec/ continuous | | |
| | P0136/56 | O2S short circuit | voltage | voltage < 0.0399 | post-cat control | Active | 100 sec/ continuous | | |



| Oxygen Sensor Monitoring – Range Rover | | | | | | | | | | |
|--|----------------|--|---|--|--|---|-------------------------|---------------------|--|--|
| Component/ System | Fault Codes | Monitoring Strategy Description | Malfunction Criteria | Threshold Value | Secondary Parameter | Enable Conditions | Time Required | MIL Illumination | | |
| | P0139/59 | oscillation capability check | if rear O2S voltage not [−] 0.625v for 0.52 sec request enrichment | enrichment request still present after 25 sec | O2S post catalyst control catalyst temperature (model) engine air flow rear O2S ready for at least rear O2S heater test rear O2S rich & lean flags not set catalyst temperature (model) | Active > 300 °C > 50 kg/h 30.0 sec completed successfully > 120 sec > 300 °C | 2.0 sec/continuous | | | |
| | | | if rear O2S voltage not m 0.625v for 0.52 Sec wait for ORFCO | rear O2S voltage > 0.20V | fuel system status integrated engine air flow whilst in ORFCO front O2S check | in ORFCO for>4.0sec > 35.0 grams completed successfully | 0.20 sec/ continuous | | | |
| Oxygen Sensor (rear) Heater | P0141/61 | O2S heater current circuit continuity | calculated resistance voltage | resistance < 2.453 ô <u>or</u> resistance > 10.06 ô | after engine start up transfer gears | > 185 sec high range | 10.0 sec/ continuous | two driving cycles | | |



4.8 Thermostat Monitoring

4.8.1 Description



The diagnostic checks for a partially open thermostat, under conditions when the thermostat would be expected to be shut.

A second ECT sensor is installed in the outlet from the radiator. If the enablement criteria are met and the ECT is less than the normal thermostat opening temperature the diagnostic will run.

The diagnostic compares the difference between ECT and the radiator outlet temperature. This gives the temperature drop across the radiator.

If the temperature drop is less than a threshold, and there is flow across the radiator, this is caused by leakage through the thermostat.



4.8.2 Monitoring Structure

